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Estimation of Bio-AerosolConcentration from Elastic Scattering LIDAR Data

November 11, 2003

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OUTLINE



- Introduction and Application
- Relevant Theory
- Forward Model
- Noise Considerations
- Inverse Model and Simulations
- Conclusion and Future Development







Introduction



- The West Desert Test Center (WDTC) at DPG uses an elastic backscatter LIDAR system to augment the tracking and characterization of bioaerosol clouds.
- In support of DPG's test mission, hardware and software development for WDTC LIDAR capability is continuing.
- This talk is a progress report on our M&S project to estimate bio-aerosol concentration from LIDAR elastic backscatter data







LIDAR Equation



A convenient form of the Lidar equation predicting the received power (in Watts), from an increment of atmosphere ΔR at range R, is

$$P(\lambda, R) = P_0 \frac{A_0}{R^2} \Delta R \, \beta_{\pi}(\lambda, \mathbf{r}) \, e^{-2 \int_0^R \kappa_e(\lambda) \, dR} \, .$$

Here λ is wave length, A_0 is area of the receiver telescope objective lens, β_{π} is the backscatter coefficient and κ_e is the extinction coefficient.







Backscatter Coefficient



The backscatter coefficient β_{π} (m $^{-1}$ sr $^{-1}$) is

$$\beta_{\pi}(\lambda, \mathbf{r}) = \int_{0}^{\infty} N(a, \mathbf{r}) \, \sigma_{b}(\lambda, a) \, da$$
.

Distribution $N(a, \mathbf{r})$ is normalized such that

$$\rho(\mathbf{r}) = \int_0^\infty N(a, \mathbf{r}) \, da \, .$$

Here $\rho(\mathbf{r})$ is number of particles per unit volume. The Mie backscattering cross-section is

$$\sigma_b(\lambda, a) = \frac{1}{k^2} \left| \frac{1}{2} \sum_{m=1}^{\infty} (2m+1)(-1)^m (a_m - b_m) \right|^2.$$







Extinction Coefficient



The extinction coefficient $\kappa_e(\lambda, \mathbf{r})$ (m⁻¹) is

$$\kappa_e(\lambda, \mathbf{r}) = \rho(\mathbf{r}) \int_0^\infty N_1(a) \, \sigma_e(\lambda, a) \, da$$

where the extinction cross section is

$$\sigma_e(\lambda, a) = \frac{2\pi}{k^2} \Re \left[\sum_{m=1}^{\infty} (2m+1) (a_m + b_m) \right].$$







Inversion of LIDAR Data



To estimate aerosol concentration, transform the measured LIDAR data to obtain

$$S(R,\lambda) = \log(R^2 P(\lambda, R) / (R_0^2 P(\lambda, R_0)).$$

This definition then yields the explicit relation

$$\frac{d}{dR}S(R,\lambda) = \frac{1}{\rho(R)}\frac{d\rho}{dR}(R) - 2\rho(R) < \sigma_e(\lambda) > .$$

This equation is solved for the particle density function $\rho(\mathbf{r})$. Necessary information includes the averaged extinction coefficient $<\sigma_e(\lambda)>$, LIDAR data $S(R,\lambda)$ and a boundary point ρ_f .









Formal Analytic Solution to Aerosol Density

$$\rho(R) = \left[(1/\rho_f + 2 < \sigma_e(\lambda)) > \int_R^{R_f} \frac{dR'}{\tau(R',\lambda)} \right] \tau(R,\lambda)$$

where

$$\tau(R,\lambda) = e^{-[S(R,\lambda) - S(R_f,\lambda)]}$$

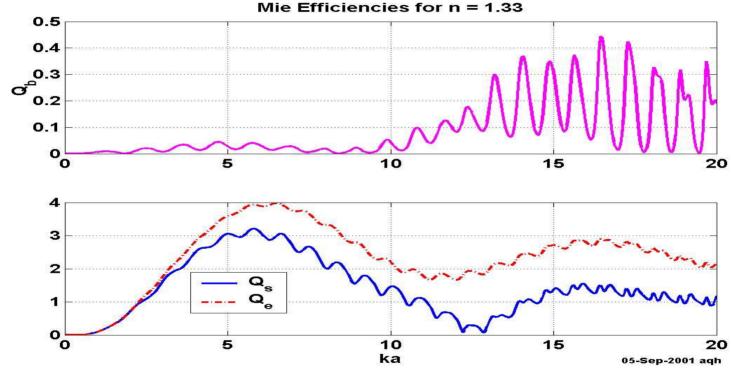






Aerosol Scattering





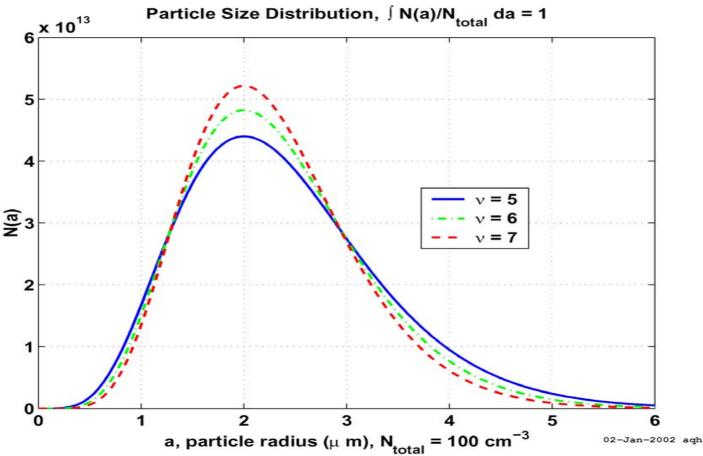
Lidar signals are proportional to Q_{b} and exponentially attenuated proportional to Q_{e}

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Aerosol Particle Size Distribution





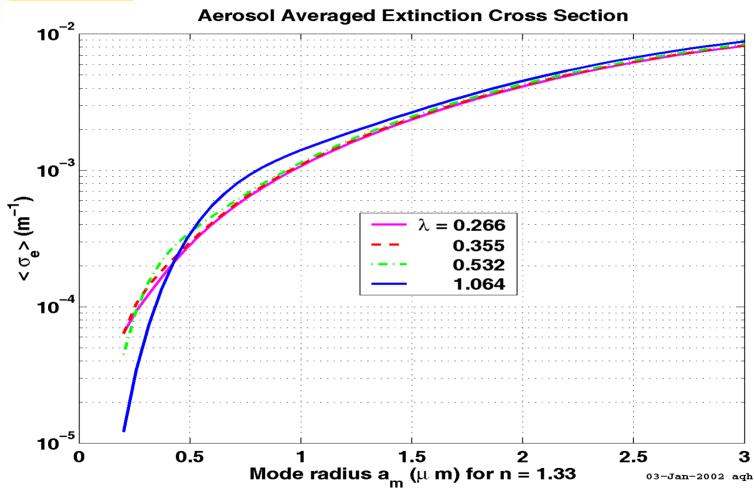






Extinction Cross Section versus Aerosol Mode Radius a_m







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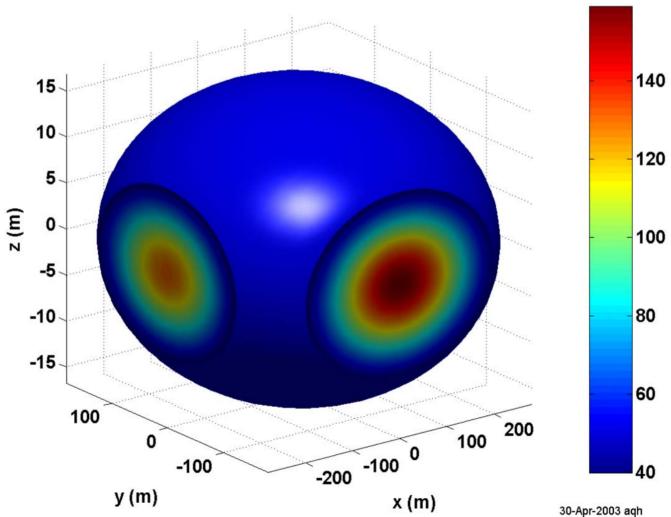




Particle Density Function



Gaussian Cloud Density $\rho(r)$ PPL

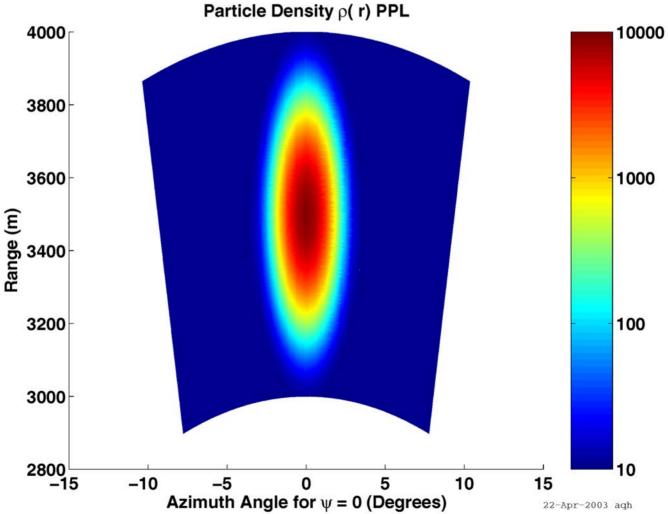






Synthetic Density Data



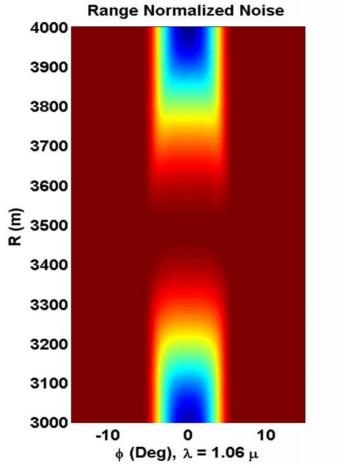


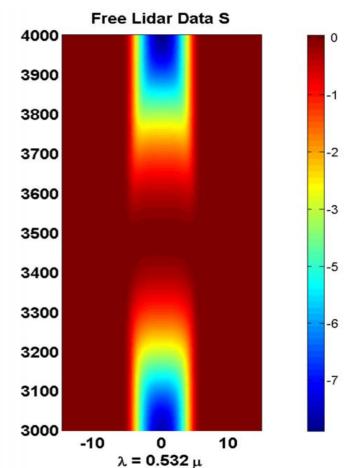




Synthetic LIDAR Data







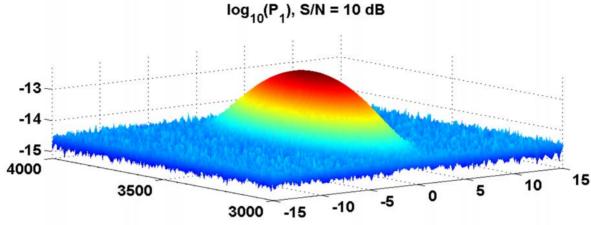


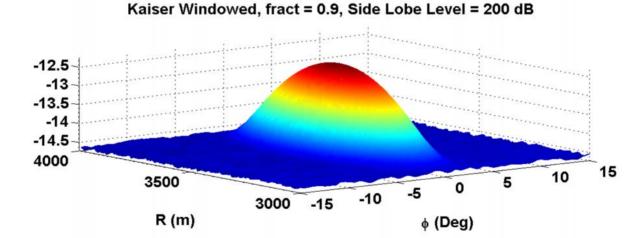












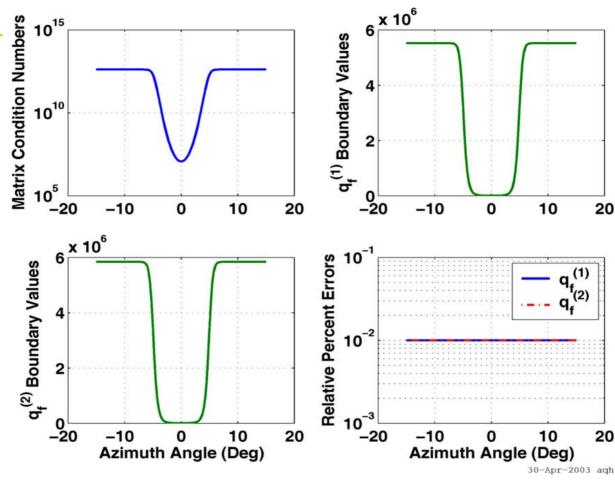
Noisy Synthetic LIDAR data $P(R, \lambda)$ for wavelength 1.064 μ . Lower panel shows effect of Kaiser window with side lobe level of 200 dB.





First Stage Inversion







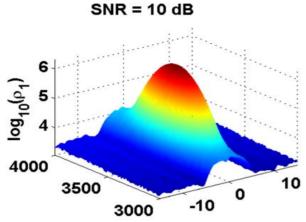
First stage inversion results using two-frequency method.

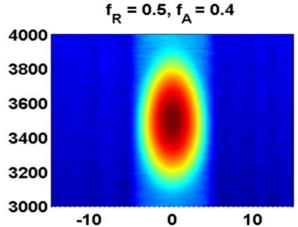


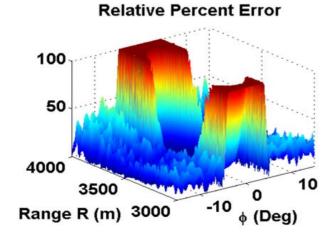


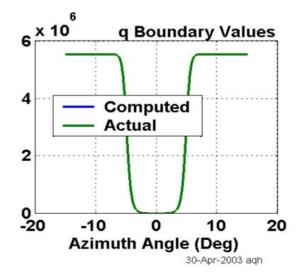
Second Stage Inversion













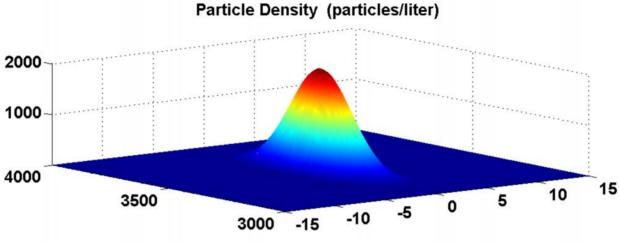
Second Stage inversion with S/N = 10 dB noise using equations for q_{nm} and point detector calibration.

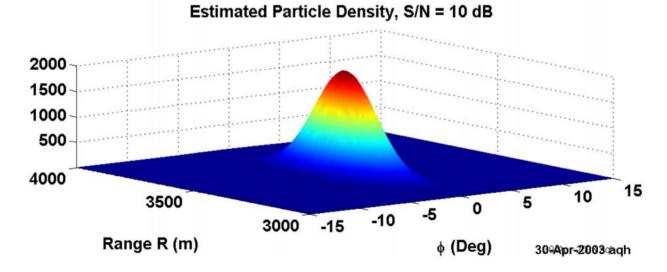




Linear Scale Inversion Results











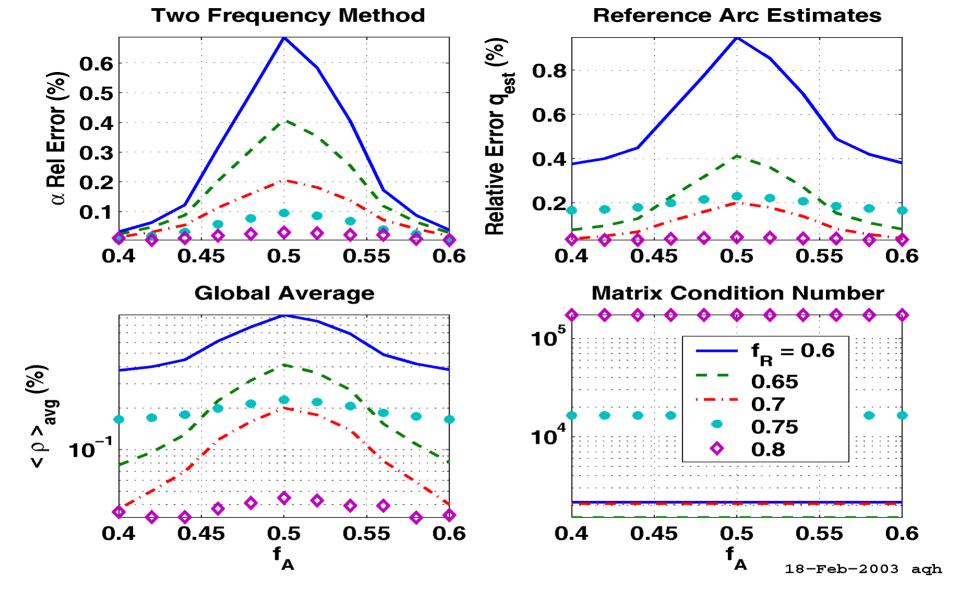


Figure 11: Inversion error analysis as a function of azimuth angle fraction f_{ϕ} with five values of f_R as shown in the legend. Upper left-hand panel is the relative percent error in the extinction coefficient estimate $\alpha^{(1)} = 2 < \sigma_e(\lambda_1) >$. The upper right panel displays the analogous percent relative errors in averaged boundary values q_f . Note the condition number is independent of f_{ϕ} .



Discrete Forward Model



$$q_{nm}^{(i)} = [V_{nm}^i + q_{fm}^{(i)}]\tau_{nm}^i,$$

where

$$\tau_{nm}^{i} = \tau(R_{n}, \phi_{m}, \lambda_{i}),$$

$$\tau(R, \phi, \lambda_{i}) = \exp[S(R, \phi, \lambda_{i}) - S(R_{f}, \phi, \lambda_{i})],$$

$$q_{nm}^{(i)} = q(R_{n}, \phi_{m}, \lambda_{i}),$$

$$q_{fm}^{(i)} = q^{(i)}(R_{f}, \phi_{m}),$$

$$q(R, \phi, \lambda_{i}) = 1/(2 < \sigma_{e}(\lambda) > \rho(R, \phi)),$$

$$V_{nm}^{i} = \int_{P}^{R_{f}} dR' / \tau(R', \phi_{m}, \lambda_{i}).$$





Density Calibration



$$\hat{
ho}_{nm} =
ho_{\mathrm{cal}} q_{\mathrm{cal}}^i / q_{nm}^i$$
 .







Single-Ray, Two-Frequency Algorithm



$$\begin{pmatrix} T_{m,a}^{(2,1)} & v_{m,a}^{(2)} \\ T_{m,b}^{(2,1)} & v_{m,b}^{(2)} \end{pmatrix} \begin{pmatrix} q_{fm}^{(1)} \\ C^{(1,2)} \end{pmatrix} = \begin{pmatrix} v_{m,a}^{(1)} \\ v_{m,b}^{(1)} \end{pmatrix},$$

where

$$T_{m,a}^{(i,j)} = 1/N_a \sum_{n=1}^{N_a} [\tau_{nm}^i - \tau_{nm}^j],$$

$$T_{m,b}^{(i,j)} = 1/N_b \sum_{n=N_b+1}^{N_R} [\tau_{nm}^i - \tau_{nm}^j].$$







where



$$v_{m,a}^{(i)} = 1/N_a \sum_{n=1}^{N_a} V_{nm}^i \tau_{nm}^i,$$

$$v_{m,b}^{(i)} = 1/N_b \sum_{n=N_a+1}^{N_a} V_{nm}^i \tau_{nm}^i,$$

$$N_a + N_b = N_R$$
.







Single-Ray, Three-Frequency Algorithm



$$\begin{pmatrix} T_{m,a}^{(2,1)} & 0 & v_{m,a}^{(2)} & 0 & 0 \\ T_{m,b}^{(2,1)} & 0 & v_{m,b}^{(2)} & 0 & 0 \\ T_{m,a}^{(3,1)} & 0 & 0 & v_{m,a}^{(3)} & 0 \\ T_{m,b}^{(3,1)} & 0 & 0 & v_{m,b}^{(3)} & 0 \\ 0 & T_{m,a}^{(2,3)} & 0 & 0 & v_{m,b}^{(2)} \\ 0 & T_{m,b}^{(2,3)} & 0 & 0 & v_{m,b}^{(2)} \end{pmatrix} \begin{pmatrix} q_{fm}^{(1)} \\ q_{fm}^{(3)} \\ C^{(1,2)} \\ C^{(1,3)} \\ C^{(3,2)} \end{pmatrix} =$$



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m,b



Conclusion & Future Work



- 2 and 3 frequency elastic scattering algorithms for particle density have been developed.
- At least 2 frequencies are necessary to determine reference arc values ρ_f .
- Ongoing work includes background removal, first stage signal-to-noise enhancement, and system conditioning.



